Conveyor system X45

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Conveyor System X45C

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Conveyor System X45H

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Introduction



Chain width 43 mm

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Chain accessories X45H69 Beams X45H70	X45
Cover strip for T-slot	XS
Slide rail tools	X65
dler end unit	X65P
Horizontal plain bends	X85
Guide rail system	X85P
Buck bondling functions V4Es for V4EC and	XH
X45H	XK
Conveyor functions for puck handling X45C and X45H80 Maximum permissible weight X45C and X45H82 Conveyor poise level X45C	XKP
Diverall installation dimensions 83 Divert functions and kits 84	X180
Merge functions and kits 86 Combined Divert/Merge 88 Transfer 91	X300
Stop	GR
Puck handling	CS

Features

The X45 is a very compact conveyor system for handling $\,WL$ small and light products.

Examples of application areas

All types of small products down to 10 mm diameter. Typical products transported directly on the conveyor are pharmaceutical bottles, perfume bottles and smaller products/packages up to 100 mm wide. Puck handling of products like test tubes for blood and urine, small bottles, cosmetics and electrical parts such as batteries.

ELV

HU

WK

- CTL

FST

- TR
- ...
- APX
- IDX

P0

CC

System information X45



Conveyor X45C and X45H

The **X45** offer includes a range of conveyor modules both for handling products directly on chain or handling X45 standard pucks.

The **X45C** conveyor is a light weight platform including both normal 3 phase AC motors and 24V DC motors with built in intelligence.

The **X45H** conveyor is a high capacity conveyor platform. It is normally used in combination with X45C when handling longer transportation and systems requiring more bends and higher speed.

Puck handling equipment X45e

X45e includes a range of function units for puck handling such as Divert, Merge, Stop or Locating. There are units handling both single pucks and train of pucks.

X45e functions includes 24V motors with embedded controls that can reduce the total lead time significantly from system design to ramp-up of the line. Each function motor include possibilities to connect to a network and in/out signals

Standard X45 pucks are available in two types, with or without lock for rotating

Divert/merge devices

Divert/merge devices are used for routing products by dividing or combining product flows. Usually there is a main conveyor, a "highway" (X45H), and separate subordinated conveyors, "satellites" (X45C).

On the satellites, products can be subjected to various operations such as turning, grinding, assembly or testing, without disturbing the main flow. After the operations, the products return to the highway.

A combination of a highway and one or more satellites is often called a cell. Using puck handling functions (X45e), it is possible to build cell junctions which facilitate transfer of a puck from one cell to another. See figure below.



Technical characteristics

System	X45C	X45H	CC
Beam width	45 mm	45 mm	X15
Chain width	43 mm	43 mm	
Chain pitch	12,7 mm	25,4 mm	XS
Drive unit capacity	100- 200 N	900N	X65
Chain tension limit	200 N (100 N Conductive)	900 N	
Item width	10-100 mm	10-100 mm	X65P
Maximum conveyor length	6 m (4 m Conductive)	25 m	X85
Maximum weight on conveyor	30 kg	125 kg	X85P
Maximum load per 100 mm conveyor length	800 g (100 g/ link)	4000 g (1000 g/ link)	ХН
Maximum single item weight, horizontal trans- port	800 g	8000 g	XKP
Conveyor speed	Variable speed 5-20 m/min	Fixed speed 5, 10, 15, 20, 30, 40, 50, 60 m/min (Max 20 with pallet)	
Horizontal plain bends:	30°/45°/90°/180°	30°/45°/90°	X300
Radius 150 mm	Note! Maximum 2 bends/con- veyor or max 270° total		GR
Horizontal wheel bends	45°/90°/180°	45°/90°/180°	cs
Vertical bends:	5°/15°	5°/15°	
Radius	400 mm	358 mm/515 mm	XT
	Note! 2 bends/conveyor (maxi- mum)		HU
Electrostatic discharge feature (ESD)	Standard/Conductive	Standard	WL
Example: Max permis product we	Max permissible puck weight ssible (base, fixture, product) inht 200 a Max 250 of nuck	Example: Max permissible puck weight Max permissible (base, fixture, product)	WΚ
Max 100 g/ link		Max 1000 g/ link	XC
	- Puck Ø 43,7	- Puck Ø 43,7 -	XF
Max permissible	e single item weight 800 g	wax permissible single item weight about g	XD
		>= 100 mm /8 links)	ELV
× >	= 100 mm (8 links) ————–		CTL

- FST
- TR
- APX
- IDX

The following guidelines must be considered when engineering conveyor:

1 Conveyor length

Maximum permissible conveyor length: See "Technical characteristics" on page 51.

2 Plain bends (only applies to X45C)

Horizontal conveyor modules can include maximum two Plain bends 30, 45, 90 or 180°. Different plain bends can be mixed, but the sum of the two bends may not exceed 270°.

Horizontal conveyor modules in conductive versions may not exceed 180°

3 Guide rails

Guide rails for straight standard conveyor modules can be adapted for products up to maximum 100 mm width. Guide rails for standard conveyor modules with horizontal bends can be adapted for products up to maximum 100x200 mm (WxL).

4 Conductive version

Conveyor modules are available in standard or conductive chain and slide rail materials versions.

5 RFID option

RFID is available for controlling puck handling functions.

Conveyor System X45C

Conveyor – introduction



Configuration of X45C

The modular conveyor system X45C makes it very easy and fast to create simple as well as advanced layouts. A range of conveyor modules can be ordered:

- Straight horizontal conveyors
- · Horizontal conveyors with one or two bends
- Vertical conveyors, transporting products from one level to another

Also a range of single and multi-lane support modules can be chosen.

The conveyor modules can be divided into:

- Standard conveyor modules
- Conveyor modules for puck handling

Configuration of X45C is done using FlexLink Online Store or the design tool FLDT.

Beam design

The X45C beams are designed for rigidness, smooth running and low noise. The T-slots ensure easy but rigid attachment of accessories such as guide rail brackets. Connecting strip kit XUCJ 50 is placed in the middle of the beam keeping the T-slots free.



APX

IDX

P0

CC

X300

Conveyor modules X45C



Chains – introduction



Friction top chain

Chain types

The conveyor chain is designed for smooth running, minimum wear and low noise level at normal speeds.

Chain

- Plain chain
- Plain chain conductive
- Friction top chain
- Friction top chain, conductive
- Flexible cleat chain

Plain chain can be used up to $5^{\circ}\pm2^{\circ}$ slopes, depending on the friction coefficient between product and chain.

Friction top chain increases the friction between product and chain and can often be used for 15° slopes.

Flexible cleat chain is used for wedge conveyors elevating products or straight horizontal transfers. -For individual weights up to 500 g

Other chains See the *Chain guid*e for a selection of other chains.



Chain installation See "Appendix "D. Chain installation" on page 533 for installation instructions.

 → → 	XKP
	X180
	X300
	GR
Friction top chain Length 3 m	CS
All links are friction type Standard material XUTP 3A45 F	хт
Conductive material XUTP 3A45 EF Friction top link kit *	HU
Standard material5113492Conductive material5113493	WL
*Link kit contains 10 friction top links,10 steel pins	WK
Flexible cleat chain	XC
43	XF
	XD
	ELV
	CTL
Flexible cleat chain XUTE 3A45 C	FST
Length 3 m Flexible cleat link kit* 5113494	TR
*Link kit contains 10 links, 10 steel pins	APX

IDX

P0

CC

XK

Beams





50

M8



To connect the Beam section for chain installation, drill a hole straight through beam with diameter 6 mm, 13 mm from the edge. (Use drill fixture 5123264)

Beams (continued)



TR

APX

IDX

Slide rail

The slide rails are designed for long service life, smooth running, low elongation and minimized risk of failure. Several options exist for high performance operation. Slide rail types include

- Type H high wear resistance (standard)
- Type E conductive

All slide rails can be mounted to the conveyor beams without using rivets for anchoring.

Two slide rail profiles

Slide rails are available in two profile designs: Slide rail for non puck-application and slide rail for puck handling.

Slide rails to be used for conveyors for puck handling						
	For straight sections	For plain bends R150	For the return side of			
		and R358	the conveyor beam			
Standard	XUCR 3 HAG	FLX1004554 and	XTCR 25 H	To be used with standard chains		
		FLX1004555				

Slide rails	to be used f	or standard conveyors
Standard	XTCR 25 H	To be used with standard chains
Conductive	XTCR 25 E	To be used with conductive chains





APX IDX

Drive and idler units X45C - introduction



Drive unit X45C

The drive unit is an active function with the main purpose of driving the chain of a conveyor. The X45C system include 24V and 380-440V drive units. Drive units are available as end drive and intermediate drive units.

24 Volt drive unit

The 24V smart motor is equipped with a permanent magnetic (PM) motor and a built in embedded controller. The unit has interfaces to PROFINET and Ethernet/IP and connections for 8 in and 4 out signals. The embedded controller enables local decisions directly down in the drive unit giving a big advantage regarding software developing, electrical design and electrical installation.

The drive unit has a variable speed ranging from 5 m/min to 20 m/min with a maximum traction force of 100N over the whole speed range. Each side is equipped with a LED indicating its status.

The drive unit has two main alternatives of receiving commands. In the local mode the drive unit starts immediately or by one of the digital input signals. In the line control mode the drive unit receives commands over the Ethernet/IP or PROFINET

If the motor are in local mode only power (24VDC) is needed to work properly

For more detailed information about the function see User documentation

380-440V drive unit

The 380-440V, 50/60Hz drive unit is available in a range of fixed speeds between 5-20m/min, see table below. The traction force depends on the speed with a maximum of 200N.

This drive is without built in intelligence or network possibilities. Start and stop function is handled by the power supply





Ordering information Drive units					PO				
Туре	Designation	Cha	in pull	Speed	d in met	ers per m	ninute 5	0/60 Hz	
		100 N	200 N	4,2/5	8,5/10	13,5/16	17/20	5-20	66
24V End drive unit, motor on left side	XUEB L B	Х						Х	X45
24V End drive unit, motor on right side	XUEB R B	Х						Х	
24V Intermediate drive unit, motor on left side	XUER L B	Х						Х	XS
24V Intermediate drive unit, motor on right side	XUER R B	Х						Х	VOF
380- 440V End drive unit, motor on left side	XUEB ML1		Х	Х					865
	XUEB ML2		Х		Х				X65F
	XUEB ML3		Х			Х			
	XUEB ML4		Х				Х		X85
380- 440V End drive unit, motor on right side	XUEB MR1		Х	Х					V850
	XUEB MR2		Х		Х				7031
	XUEB MR3		Х			Х			XH
	XUEB MR4		Х				Х		
380- 440V Intermediate drive unit, motor on left or right side	XUER M1 A	Х		Х					XK
	XUER M2 A	Х			Х				ХКР
	XUER M3 A	Х				Х			
	XUER M4 A	Х					Х		X180

End drive units

GR End drive unit, 380 V-440 V, 40 W End drive unit, 24 V, 40 W CS 220 100 60 🗝 130 XT 42 80 170 185 210 205 HU WL **↓**190/207→ 80 55 WK End drive unit Maximum traction force: up to 200 N. XC Maximum permissible speed: 20 m/min. End drive unit Maximum traction force: up to 100 N. Motor on left side: XF Maximum permissible speed: 20 m/min. Fixed speed * XUEB ML Motor on left side: XD Without motor **XUEB MLO** Variable speed * **XUEB L B** Motor on right side (not shown): ELV Motor on right side (not shown): Fixed speed * XUEB MR Variable speed * **XUEB R B** CTL Without motor **XUEB MR0** Effective track length: 0,125 m (Height 185 mm to center T-slot) Effective track length: 0,125 m FST (Height 170 mm to center T-slot) *See table "Ordering information Drive units" *See table "Ordering information Drive units" TR

IDX

X300





IDX

Basic units



Idler units





-145

Ø272

Connecting strips are included.

Wheel bend, 90°

60



IDX

Plain bends

Plain bends





Item no	Angle (a)	Radius (R)	Length (L)
XUBP 30R150	30° ±1°	150 ±5 mm	160 mm
XUBP 30R210	30° ±1°	210 ±5 mm	190 mm
XUBP 45R150	45° ±1°	150 ±5 mm	190 mm
XUBP 45R210	45° ±1°	210 ±5 mm	232 mm
XUBP 90R150	90° ±1°	150 ±5 mm	212 mm
XUBP 90R210	90° ±1°	210 ±5 mm	272 mm
XUBP 180R150	180° ±1°	150 ±5 mm	212 mm
XUBP 180R210	180° ±1°	210 ±5 mm	272 mm
XUBP 45TYP5	15°-45° ±1°	R=210-500 ±10 mm	
XUBP 90TYP5	46°-90° ±1°	R=210-500 ±10 mm	
XUBP 45TYP10	15°-45° ±1°	R=501-1000 ±10 mm	
XUBP 90TYP10	46°-90° ±1°	R=501-1000 ±10 mm	
	(Maximal _{tot} 270°)		

Plain bend, 30°	
Effective track lengths: R150: 0,16 m 1-way (0,32 m 2-way)	XUBP 30R150
Effective track lengths: R210: 0,20 m 1-way (0,40 m 2-way)	XUBP 30R210
Plain bend, 45°	
Effective track lengths:R150: 0,21 m 1-way (0,42 m 2-way)	XUBP 45R150
Effective track lengths:R210: 0,25 m 1-way (0,50 m 2-way)	XUBP 45R210
Plain bend, 90°	
Effective track lengths:R150: 0,34 m 1-way (0,68 m 2-way)	XUBP 90R150
Effective track lengths:R210: 0,43 m 1-way (0,86 m 2-way)	XUBP 90R210
Plain bend, 180°	
Effective track lengths:R150: 0,60 m 1-way (1,2 m 2-way)	XUBP 180R150
Effective track lengths:R210: 0,90 m 1-way (1,8 m 2-way)	XUBP 180R210
Plain bend, 15°-45°, 46°-90°	
Plain bend, 15°-45°±1°, R=210-500 ±10 mm	XUBP 45TYP5
Plain bend, 46°-90°±1°, R=210-500 ±10 mm	XUBP 90TYP5
Plain bend, 15°-45°±1°, R=501-1000 ±10 mm	XUBP 45TYP10
Plain bend, 46°-90°±1°, R=501-1000 ±10 mm	XUBP 90TYP10

30

Vertical bends



Enclosure components X45C and X45H Cable cover





Cable cover Plastic Including mounting details

5113038

	GR
Guide rail system	CS
See "Guide rail components" on page 299	XT
Conveyor support	HU
See "Conveyor support components" on page 337	WK
	XC
	XF
	XD
	ELV
	CTL
	FST
	TR
	APX

Conveyor System X45H

Conveyor - introduction

The X45H conveyor is high capacity conveyor system for handling small products and can easily integrated with X45 conveyors enable the advantage of running longer conveyors with more bends and with higher speed than X45.

Puck handling

The standard pucks for X45 can run on the X45H conveyors. Slide rails with integrated rail for puck handling are available for straight conveyors as well as for bends.

A number of puck handling functions for diverting and merging is available.



The standard guide components can be used.

Beam design

The X45H beams are designed for rigidness, smooth running and low noise. The T-slots ensure easy but rigid attachment of accessories such as guide rail brackets.



Cross-section of straight section conveyor beam with slide rails for non puck application

Cross-section of straight section conveyor beam with slide rails for puck application

Chains – introduction



Chain types	CC
The conveyor chain is designed for smooth	X45
speeds.	XS
Chain • Plain chain	X65
Plain chain can be used up to $5^{\circ}\pm2^{\circ}$ slopes, depending on the friction coefficient between product and chain.	X65P
	X85
Chains X45H	X85P
Plain chain	ХН
	ХК
	XKP
H H	X180

P0

X300

GR

CS

5114508

Chain accessories X45H



Plain chain Length 5 m

Beams X45H



Cover strip for T-slot



XC

XF

XD

ELV

CTL

FST

TR

APX

IDX

Slide rails



Note. Kit contains 2 pcs. Included in FLX1004836,

FLX1004837 and FLX1004838

Slide rail tools



XF

- XD
- ELV
- CTL
 - FST
 - TR
 - APX
 - IDX

Drive unit types

The X45H system includes direct drive units, Heavy and Medium

Available motors include variable speed types (V) as well as fixed speed motors (F).

End drive units



Motor specifications

Motors are available for 230/400 V, 50 Hz and 230/460 V, 60 Hz. Variable speed motors are SEW Movimot, 380–500 V. Note that variable speed motors include a control box that adds 120 mm to the width of the motor.

IP55 available with standard oil.

IP65 available with food grade oil.

Ordering information

Drive units with motors must be specified using the webbased configurator. The configurator provides detailed information and step-by-step guidance in the specification process. A product code string is generated, containing the specification details. See section CC for examples of code strings.

Drive units *without* motors can be ordered using the designations in the catalogue.

Dimension

Note that dimensions relating to drive unit motors depend on the motor specified during the configuration.

End drive units



XF

XD

ELV

CTL

FST

TR

APX

IDX

End drive unit X45H, Mid drive



- End drive unit, configured item* Fixed speed: 5- 10- 15- 20 m/min*
- End drive unit, Mid 50/60 Hz 230/400 V

XTEB DD

* Use online configurator when ordering Effective track length: 2x0,80 m

End drive unit NLPD/NRPD



Idler end unit



Wheel bends



FST

- TR
- APX
- IDX

Horizontal plain bends







Effective track lengths: R358: 0,70 m 1-way (1,40 m 2-way) R518: 0,85m 1-way (1,70 m 2-way)

Enclosure compone	nts X45C and X45H	PO
Cable cover		CC
		X45 XS
S		X65
		X65P
	ATTER S	X85
		X85P
Cable cover	5113038	XH
Plastic	5113036	ХК
	5	ХКР
Guide rail system		X180
See "Guide rail componer	its" on page 299	X300
Convevor support		GR
See "Conveyor support co	omponents" on page 337	CS
		XT
		HU
		WL
		WK
		XC
		XF
		XD
		ELV
		CTL
		FST
		TR

- APX
- IDX

Puck handling functions X45e for X45C and X45H

Conveyor functions for puck handling X45C and X45H

Conveyor function kits for puck handling are used for handling individual products on standard pucks (carrier) XUPP 43 and XUPP 43 T. A whole range of functions such as Divert, Merge, Combined Divert/ Merger, Stop and Locating can easily be integrated to X45C and X45H conveyors.

This makes it easy and fast to create layouts for routing, balancing, buffering and positioning of pucks. RFID identification in the pucks enables one piece track and trace and logistic control for the production line.

Typical conveyor layouts for puck handling

The figures shows a typical conveyor layouts for puck handling. A system that includes a mix of X45C and X45H conveyors with X45e kits for handling the puck functions in the system.



Configuration X45e kit for X45C and X45H

Functional X45e kits are available with the following functions: Divert, Merge, Combined Divert/Merge, Transfer, Locate and Stops.

Configuration procedure

All functions are delivered with an assembly instruction that contains detailed information about or how to:

- Bill of material (BOM)
- Function origin.

(Identification of the function origin. All components are mounted from this point.)

- Cutting Slide Rail
- · How to cut different types
- Motor Assembly
- Mounting Motor
- Mounting Guide Rails
- Mounting Sensors

The instructions are included with the kit or can be downloaded at our website www.flexlink.com



The control system for the platforms X45e is structured in an object oriented way. All puck function motors in the platform have embedded control units and local sensors are connected directly to each motor unit. This layout gives a big advantage regarding software developing, electrical design and electrical installation.

Function control

The motor unit consists of a motor, circuit boards and eight connectors in an encapsulated housing. There are two types of motor units, the drive unit and the function unit. All that differs on these variants are the motor and the mechanical housing.

Function units X45e

Each function unit includes an embedded controller for handling local decisions within the function area. The unit is equipped with 8 input signals and 4 output signals for connection to sensors and other function units and equipment. The motor unit has a LED on each side indicating the status.

The motors can be autonomously controlled only by the input of the local sensors or controlled from a line controller over a EtherNet/IP or PROFINET network.

If the motors are in autonomous mode they only need power (24VDC) to work properly.

All software in the X45*e* motors are preloaded and the behavior of the motors can be adjusted to different performance (such as function type, speed and angle settings) by connecting a computer via the USB connector

For more detailed information about the function see User documentation

Line control and power

A line controller can be interlinked via an external Ether-GR Net/IP or PROFINET network. RFID reader/writers can be connected to the same network via a control interface unit. All dynamic route handling has to be implemented in CS the line controller. The main electrical cabinet supplies the motor units with power, 24 VDC. The power is divided XT in safe and continuous power in order to have the possibilities to implement emergency or safety stops.

HU X45e units equipped with the old version of Device NET Interface are available to order as RFQ item. Contact FlexLink for more info. WL

WK
XC
XF
XD
ELV
CTL
FST
TR
APX
IDX

Diverters, Mergers, Combined Diverters/Mergers and Transfers for Puck handling



Diverters

Diverters are used to split a flow of pucks from one line into two. The lines can be parallel or in a 90° angle.

	DR 🔺 🔺	DL 🔺	DR 🔺
			-
)	lí	90°	90°

Mergers

Mergers are used to combine the flow from two lines into one. The lines can be parallel or in a 90° angle.



Combined Diverter/merger

A combined diverter/merger is used to create a sub line for example to guide pucks out and in on a satellite conveyor from the main conveyor. They can also be used as "shortcuts".



Transfers

Transfers are used to transfer the puck between the conveyors in a system. The parallel transfers are passive but the 90° and 180° angled transfers are driven by a motor.



Maximum permissible weight X45C and X45H



The diagram shows the maximum permissible weight of a group of pucks (product weight + puck weight) that the functions Divert, Merger, Combined Diverter/Merger, Stop and Locating are capable stopping, as a function of the conveyor speed.



Divert functions and kits

The diverter is an active unit with one infeed and two outfeed conveyors.

There are four different variants of the diverter.

- Diverter, Parallel, Left
- Diverter, Parallel, Right
- Diverter, 90°, Left
- Diverter, 90°, Right

The unit has two positions for photoelectric sensors. The first one is used for sensing the queue status of the infeed conveyor. This sensor can be replaced by a RFID read/write head.

When a puck arrives the rotation disc opens up to receive the puck. The second sensor is used for detecting that the puck has reached the gap of the rotation disc. This is the trigger signal for the main rotation of the rotation disc, with a puck in the gap.

The decision of which outfeed conveyor to release the puck on can be received from the external bus, via a local sensor or from a predetermined pattern.

For more detailed information about the function, see User documentation in Technical library at *flexlink.com*





Function		Direction	Designation	l avout	PU
		Diverter kit X45C<=>X45, Left	XUPJ 43 DL B		CC
		Diverter kit X45H<=>X45C, Left	XUPJ 43 DLH B		X43 XS
	Parallel	Diverter kit X45H<=>X45H, Left	XTPJ 43 DL B		X65
	T dialion	Diverter kit X45C<=>X45, Right	XUPJ 43 DR B	↑ ↑	X65F
Divert		Diverter kit X45H<=>X45C, Right	XUPJ 43 DRH B		X85
		Diverter kit X45H<=>X45H, Right	XTPJ 43 DR B		X85F
		Diverter 90° kit X45C<=>X45C, Left	XUPJ 43 DL 90 B		ХН
	000	Diverter 90° kit X45H<=>X45C, Left	XUPJ 43 DL 90HB		XK
	90-	Diverter 90° kit X45C<=>X45C, Righ	XUPJ 43 DR 90 B		XKP
		Diverter 90° kit X45H<=>X45C, Right	XUPJ 43 DR 90HB		X300
					GR

Function structure list Divert functions and kits

CS

ΧT

ΗU

WL

WK

XC

XF

XD

ELV

CTL

FST

TR

APX

IDX

Merge functions and kits

The merger is an active unit with two infeed and one out-feed conveyor.

There are four different variants of the merger.

- Merger, Parallel, Left
- Merger, Parallel, Right
- Merger, 90°, Left
- Merger, 90°, Right

The unit has two sets of guide brackets each containing two photoelectric sensors. The first sensor position on each side is used for sensing the queue status of the infeed conveyors. These queue sensors are the trigger signal for the merger to move the rotation disc to one of the two receive positions. This is done either clockwise or counter clockwise depending on which conveyor to receive pucks from.

The last sensor is used for sensing pucks in the gap of the rotation disc. This is the trigger signal for the main rotation of the rotation disc, with a puck in the gap. When the rotation disc has reached the release position the cycle is complete and the unit waits for a new puck to arrive.

For more detailed information about the function, see User documentation in Technical library at *flexlink.com*





Function structure list, Merger functions and kits

Function		Direction	Designation	Layout	CC	
Parallel		Merger kit X45C<=>X45C, Left	XUPJ 43 ML B		X45	
	Parallel	Merger kit X45H<=>X45C, Left	XUPJ 43 MLH B			XS
		Merger kit X45H<=>X45H, Left	XTPJ 43 ML B		X65	
		Merger kit X45C<=>X45C, Right	XUPJ 43 MR B			X65P
Merge 90°		Merger kit X45H<=>X45C, Right	XUPJ 43 MRH B		X85	
		Merger kit X45H<=>X45H, Right	¹ , XTPJ 43 MR B		X85P XH	
	90°	Merger 90° kit X45<=>X45C, Left	XUPJ 43 ML 90 B		ХК	
		Merger 90° kit X45H<=>X45C, Left	XUPJ 43 ML 90HB		ХКР	
		Margar Q0° kit X450 <-> X450			X180	
		Right	XUPJ 43 MR 90 B		X300	
		Merger 90° kit X45H<=>X45C, Right	XUPJ 43 MR 90HB		GR	
	1	1			CS	

P0

XT

ΗU

WL

WK

XC

XF

XD

ELV

CTL

FST

TR

APX

IDX

Combined Divert/Merge

A Combined Diverter/Merger is used to create a sub line for example to guide pucks out and in on a satellite conveyor from the main conveyor. They can also be used as "shortcuts". This function has the behaviour from both the diverter and the merger. The prioritized order can be predetermined or decided dynamically from a line controller.

For more detailed information about the function, see User documentation in Technical library at *flexlink.com*



Function structure list, Combined Diverter/Merger

Function		Direction	Designation	Layout
		Combined Divert/Merge kit X45C<=>X45C, Left	XUPJ 43 CL B	
		Combined Divert/Merge kit X45C<=>X45H, Left	XUPJ 43 CLH B	
	Darallal	Combined Divert/Merge kit X45H<=>X45H, Left	XTPJ 43 CL B	
Combined Divert/Merge 90°	Falaliei	Combined Divert/Merge kit X45C<=>X45C, Right	XUPJ 43 CR B	
		Combined Divert/Merge kit X45C<=>X45H, Right	XUPJ 43 CRH B	
		Combined Divert/Merge kit X45H<=>X45H, Right	XTPJ 43 CR B	
	90°	Combined Divert/Merge kit X45C<=>X45C, Left	XUPJ 43 CL 90 B	↑
		Combined Divert/Merge kit X45C<=>X45H, Left	XUPJ 43 CL 90HB	
		Combined Divert/Merge kit X45C<=>X45C, Right	XUPJ 43 CR 90 B	
		Combined Divert/Merge kit X45C<=>X45H, Right	XUPJ 43 CR 90HB	

P0

CC

X45

XS

X65

X65P

X85

X85P

XH

XK

XKP

X180

X300

GR

CS

XT

ΗU

WL

WK

XC

XF

XD

ELV

CTL

FST

TR

APX

IDX

Combined Diverter/Merger for handling train of products

This combined diverter/merger unit is handling train of products. It require a gap in the product flow during function operation change. Gaps are normally created by stop units located on each incoming conveyor. The decision of which outfeed conveyor to release the pucks on can be received from the external bus, via a local sensor or from a predetermined pattern. For more detailed information about the function, see User documentation in Technical library at flexlink.com

Function	Direction	Designation	Function alternatives
Combined Divert/Merge Train product handling	Diverter/Merge kit X45C<=>X45	XUPJ 43 DT B	\rightarrow
	Diverter/Merge kit X45H<=>X45C,	XUPJ 43 DTH B	\rightarrow
	Divert/Merge kit X45H<=>X45H	XTPJ 43 DT B	$\rightarrow \rightarrow$

Transfer

Transfers are used to transfer the puck between the conveyors in a system.

Т

For more detailed information about the function, see User documentation in Technical library at *flexlink.com*



ransfer 180°	CC
	X45
	XS
	X65
	X65P
	X85
	X85P
	хн
ransfer kit 180° X45C<=>X45C XUPJ 43 T_ 180 B ransfer kit 180° X45H<=X45C XUPJ 43 T_ 180 HB	ХК
ransfer kit 180° X45H<=>X45H XTPJ 43 T_ 180 B Figure shows type L (transfer to left)	XKP
Ise online configurator when ordering	X180
	X300
	GR
	CS
	XT
	HU
	WL
	WK
	XC
	XF
	XD
	ELV
	CTL
	FST
	TR
	APX
	IDX

Function structure list, Transfer, parallel and 90°

Function		Direction	Designation	Layout	
		Transfer kit, parallel, left, X45C<=>X45	XUPJ 43 T	Л	
		Transfer kit, parallel, left, X45H<=>X45C	XUPJ 43 TH		
	Parallal	Transfer kit, parallel, left, X45H<=>X45H	ХТРЈ 43 Т		
	raialiti	Transfer kit, parallel, right, X45C<=>X45C	XUPJ 43 T		
		Transfer kit, parallel, right, X45H<=>X45C	XUPJ 43 TH		
Transfer		Transfer kit, parallel, right, X45H<=>X45H	ХТРЈ 43 Т		
	90°		Transfer kit, 90, left, X45C<=>X45C	XUPJ 43 TL 90 B	
		Transfer kit, 90, left, X45H<=>X45C	XUPJ 43 TL 90HB		
		Transfer kit, 90, right, X45C<=>X45C	XUPJ 43 TR 90 B		
		Transfer kit, 90, right, X45H<=>X45C	XUPJ 43 TR 90HB		

Function structure list, Transfer 180°

Function		Direction	Designation	Layout
Transfer 18		Transfer kit, 180, left, X45C<=>X45C	XUPJ 43 TL 180B	
		Transfer kit, 180, left, X45H<=X45C	XUPJ 43 TL 180HB	
		Transfer kit, 180, left, X45H=>X45C	XTPJ 43 TL 180UB	
	1900	Transfer kit, 180, left, X45H<=>X45H	XTPJ 43 TL 180B	
		Transfer kit, 180, right, X45C<=>X45C	XUPJ 43 TR 180B	
		Transfer kit, 180, right, X45H<=X45C	XUPJ 43 TR 180HB	
		Transfer kit, 180, right, X45H=>X45C	XTPJ 43 TR 180UB	
		Transfer kit, 180, right, X45H<=>X45H	XTPJ 43 TR 180B	

X180

X300

GR

CS

ΧT

HU

WL

WK

XC

XF

XD

ELV

CTL

FST

TR

APX

IDX

XKP

P0

CC

X45

XS

X65

X65P

X85

X85P

XH

XK

Stop unit is an active unit acting on a single conveyor.

The unit has only one photoelectric sensor. This detects a puck in the queue. The default position of the stop unit is closed, i.e. it is able to resist a queue of pucks. If the stop is deactivated the unit opens up to receive a puck.

This unit can be controlled either via the external bus or in local mode by a signal in the local digital input.

For more detailed information about the function, see User documentation in Technical library at *flexlink.com*



Function structure list, Stop unit

Function	Direction	Designation	Layout
Stop unit Single product handling	Stop unit kit, X45C Left	XUPD 43 L B	
	Stop unit kit, X45H Left	XTPD 43 L B	
	Stop unit kit, X45C Right	XUPD 43 R B	
	Stop unit kit, X45H Right	XTPD 43 R B	

Function	Direction	Designation	Layout	
Stop unit Train product handling	Stop unit kit, X45C Left	XUPD 43 LT B		
	Stop unit kit, X45H Left	XTPD 43 LT B		
	Stop unit kit, X45C Right	XUPD 43 RT B		
	Stop unit kit, X45H Right	XTPD 43 RT B		

Locating unit

Locating unit is an active unit acting on a single conveyor.

The station has only one photoelectric sensor. This is detecting that the puck has reached the gap of the rotation disc. The locating station can also be equipped with a RFID read/write head on the locating position. The station can be controlled either via the external bus or using only local control.

For more detailed information about the function, see User documentation in Technical library at *flexlink.com*



ocating unit, with bypass		CC
		X45
		XS
		X65
	206	X65P
		X85
		X85P
ocating unit X45C kit		XH
Locating accuracy ± 0.5 mm Angle accuracy $\pm 2^{\circ}$		XK
Use online configurator when orderir	ng	XKP
ngure shows type night		X180
		X300
		GR
		CS
		XT
		HU
		WL
		WK
		XC
		XF
		XD
		ELV
		CTL
		FST

- TR
- APX IDX

Function structure list, Locating unit

Function	Direction	Designation	ltem	Layout		
Locating unit	X45C, Left, kit	XUPX 43 OL B				
	X45H, Left, kit	XTPX 43 OL B				
	X45C, Right, kit	XUPX 43 OR B				
	X45H, Right, kit	XTPX 43 OR B				
Locating unit, end of satellite	X45C, Left, kit	XUPX 43 SL B				
	X45C, Right, kit	XUPX 43 SR B				
Locating unit, locating with by- pass	X45C, Left, kit	XUPX 43 OBL B				
	Note: Do not use with puck XUPP 43 TA					
	X45C, Right, kit	XUPX 43 OBR B				
	Note: Do not use with puck XUPP 43 TA					
XUPP 43	XUPP 4	The rotating disc the conveyor into function included puck towards a v- puck is locked ve forces e.g. unload aloud in the X, Y Accuracy: Locating ±0,5 Angle ± 2°	guides the puck sideways out of o the locating position. A spring l in the rotating disc presses the shaped block. In this position the rtical and can take limited vertical d or load a test tube. No loads are -plane.			
B) Can only be used with XUPP 43 and XUPP 43 TA.						

Puck handling

A complete Puck XUPP 43 or XUPP 43 TA consists of a base and a ring part.

Function of the ring is to allow the function disc in all different function units, to rotate without getting force from the other pucks that can be in queue in a line up situation.







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RFID components

RFID tag

The RFID tag is a circular tag with a diameter of 30 mm operating at the frequency of 13.56 MHz. The memory available is 1024 bit or 16 kbit.

Read/ write head

The read/write head exchanges data with the passive RFID tags at a maximum distance of 50 mm.

The read/write head has an M12 connector. The M12 cable is connected to a control interface unit.

Control interface unit

Every read/write head has to be connected to a control interface unit. These units exist in different variants that can connect up to four read/write heads each.

They are equipped with interfaces for some of the most common field bus system, Profibus, PROFINET, Ethernet and DeviceNet and Interbus, as well as with serial interfaces.

For more detailed information about the function, see User documentation.



RFID Reader/writer for X45 and X45H Image: state of the s

RFID Reader/writer locating station



Sensor maximum queue

In order to prevent any jam in the production flow, a maximum queue sensor can be connected. It will read if a unexpected long queue occurs, a signal will be received by the embedded software in previous function motor in the flow and stop the feed or feed through to another flow



Maximum queue



P0

GR

CS

XT

HU

WL

WK

XC

XF

XD

ELV

CTL

FST

TR

APX

IDX